

Randomized subspace methods for high-dimensional model-based derivative-free optimization

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Based on joint works with Warren Hare and Amy Wiebe

Derivative-free optimization (DFO)

Consider the optimization problem

$$\min_{x \in \mathbb{R}^n} f(x)$$

where f is given by a blackbox:



Derivative-free optimization is the mathematical study of optimization algorithms that do not use derivatives

Note: It does not mean that the derivatives do not exist

Model-based DFO methods:

- Use function values to build an approximation model of the objective
- Use the model to guide future iterations

Limitations:

- Number of function evals. is too high for large problems ($n \approx 1000$)
- Primarily designed for small- to medium-scale problems ($n \leq 100$)

Randomized subspace model-based DFO

Idea:

1. Select a low-dimensional affine subspace
2. Build and optimize a model to compute a step in this subspace
3. Change the affine subspace at the next iteration

Model-based trust-region (MBTR) algorithm

for $k = 0, 1, \dots$ **do**

Construct a model m_k in $\mathbb{R}^n$:

$$m_k(s) = f(x_k) + g_k^\top s + \frac{1}{2} s^\top H_k s$$

Approximately solve the trust-region subproblem in $\mathbb{R}^n$:

$$s_k \approx \underset{s \in \mathbb{R}^n}{\operatorname{argmin}} m_k(s), \quad s.t. \quad \|s\| \leq \Delta_k$$

Evaluate $f(x_k + s_k)$ and apply descent ratio test

$$\rho_k = \frac{f(x_k) - f(x_k + s_k)}{m_k(\mathbf{0}) - m_k(s_k)} = \frac{\text{true decrease}}{\text{predicted decrease}}$$

Accept/reject step based on ρ_k and update trust region radius

Model quality requirement: Q -fully linear models

Definition. A model $m : \mathbb{R}^n \rightarrow \mathbb{R}$ is **fully linear** in $B(x, \Delta)$ if there exist $\kappa_f(x), \kappa_g(x) > 0$ s.t. for all $s \in \mathbb{R}^n$ with $\|s\| \leq \Delta$,

$$\begin{aligned} |f(x+s) - m(x+s)| &\leq \kappa_f(x) \Delta^2 \\ \|\nabla f(x+s) - \nabla m(x+s)\| &\leq \kappa_g(x) \Delta \end{aligned}$$

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Definition. [Cartis, Roberts, 2023]

Let $Q \in \mathbb{R}^{n \times p}$. A model $\widehat{m} : \mathbb{R}^p \rightarrow \mathbb{R}$ is **Q -fully linear** in $B(x, \Delta)$ if there exist $\kappa_f(x), \kappa_g(x) > 0$ s.t. for all $\widehat{s} \in \mathbb{R}^p$ with $\|\widehat{s}\| \leq \Delta$,

$$\begin{aligned} |f(x + Q\widehat{s}) - \widehat{m}(\widehat{s})| &\leq \kappa_f(x) \Delta^2 \\ \|Q^\top \nabla f(x + Q\widehat{s}) - \nabla \widehat{m}(\widehat{s})\| &\leq \kappa_g(x) \Delta \end{aligned}$$

Note: Check out [Chen, Hare, Wiebe, 2024] for construction & management procedures!

Subspace quality requirement: α -well-aligned matrices

Let $x + D\mathbb{R}^p$ be the affine subspace

Definition. [Cartis, Roberts, 2023]

Let $\alpha \in (0, 1)$. We say that $D \in \mathbb{R}^{n \times p}$ is α -well-aligned for f at x if

$$\left\| D^\top \nabla f(x) \right\| \geq \alpha \left\| \nabla f(x) \right\|$$

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Theorem. [Dzahini, Wild, 2024] (Idea: Johnson–Lindenstrauss Lemma)

Let $\alpha, \delta \in (0, 1)$. Suppose $p \geq 4(1 - \alpha)^{-2} \ln(1/\delta)$ and let $D_{ij} \sim \mathcal{N}(0, 1/p)$. Then,

$$\mathbb{P}[D \text{ is } \alpha\text{-well-aligned for } f \text{ at } x] \geq 1 - \delta$$

A quick comparison

	[CartisRoberts23]	[DzahiniWild24]	[ChenHareWiebe24]
Problem	Deterministic	Stochastic	Deterministic
Model	Linear	Linear	Quadratic
Sample set	Completely resample	Completely resample	Reuse previous points
Subspace	No discussion on p	Lower bound on p	Lower bound on p_{rand}

Looks good, but...

Haha, my problem has constraints!

(C, Q) -fully linear models

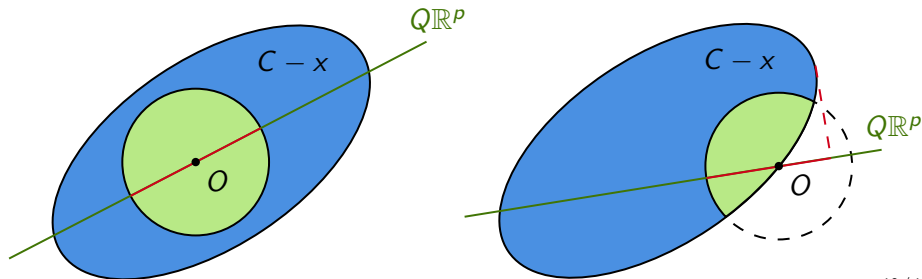
Let C be the constraint set (convex, closed, nonempty interior)

Definition. [Chen, Hare, Wiebe, 2025]

Let $Q \in \mathbb{R}^{n \times p}$. A model $\widehat{m} : \mathbb{R}^p \rightarrow \mathbb{R}$ is (C, Q) -fully linear in $B(x, \Delta)$ if there exist $\kappa_f(x), \kappa_g(x) > 0$ s.t. for all $\widehat{s} \in Q^\top(C - x)$ with $\|\widehat{s}\| \leq \Delta$,

$$|f(x + Q\widehat{s}) - \widehat{m}(\widehat{s})| \leq \kappa_f(x)\Delta^2$$

$$\max_{\substack{d \in Q^\top(C-x) \\ \|d\| \leq 1}} \left| \left(Q^\top \nabla f(x + Q\widehat{s}) - \nabla \widehat{m}(\widehat{s}) \right)^\top d \right| \leq \kappa_g(x)\Delta$$



α -well-aligned matrices (convex-constrained version)

Let $x + D\mathbb{R}^p$ be the affine subspace and $D = QR$ be the QR factorization

Definition. [Chen, Hare, Wiebe, 2025]

Let $\alpha \in (0, 1)$. We say that $D \in \mathbb{R}^{n \times p}$ is α -well-aligned for f and C at x if

$$\left| \min_{\substack{d \in C-x \\ \|d\| \leq 1}} \nabla f(x)^\top Q Q^\top d \right| \geq \alpha \left| \min_{\substack{d \in C-x \\ \|d\| \leq 1}} \nabla f(x)^\top d \right|$$

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Theorem. [Chen, Hare, Wiebe, 2025]

(Idea: Concentration on the Grassmannian)

Suppose $p \geq n\alpha$ and let $D_{ij} \sim \mathcal{N}(0, 1)$. Then,

$$\mathbb{P}[D \text{ is } \alpha\text{-well-aligned for } f \text{ and } C \text{ at } x]$$

$$\geq \text{complicated stuff that depends on } n, p, \alpha, \pi^f(x), \text{ and } \|\nabla f(x)\|$$

Convergence and complexity results

Let $\epsilon > 0$, (UC)=UnConstrained, and (CC)=Convex-Constrained

- (UC) $\mathbb{P} \left[\inf_{k \geq 0} \|\nabla f(x_k)\| = 0 \right] = 1$
(CC) $\mathbb{P} \left[\inf_{k \geq 0} \pi^f(x_k) = 0 \right] = 1$
- (UC) $\mathbb{E} [\min \{k \geq 0 : \|\nabla f(x_k)\| < \epsilon\}] = \mathcal{O}(\epsilon^{-2})$
(CC) $\mathbb{E} [\min \{k \geq 0 : \pi^f(x_k) < \epsilon\}] = \mathcal{O}(\epsilon^{-4})$

Summary

In summary,

- High-dimensional DFO problems are hard
- Unconstrained problems can be effectively approached by randomized subspace methods
- Randomized subspace methods work for convex constrained problems, but the projection onto the feasible set is required

Future directions:

- Nonconvex constraints?
- Blackbox constraints?
- Random manifolds?

Thank you

- Y. Chen, W. Hare, and A. Wiebe. “Q-fully quadratic modeling and its application in a random subspace derivative-free method”. In: *Computational Optimization and Applications* 89.2 (2024), pp. 317–360
- Y. Chen, W. Hare, and A. Wiebe. “CLARSTA: A random subspace trust-region algorithm for convex-constrained derivative-free optimization”. In: *arXiv preprint arXiv:2506.20335* (2025)

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