## Adjusting the Centred Simplex Gradient to Compensate for Misaligned Sample Points

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Joint work with Dr. Warren Hare

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## Outline



- Adapted Centred Simplex Gradient
- 3 Error analysis
- 4 Numerical experiments
- 5 Conclusions

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## Simplex Gradient, SG

#### Consider

$$f:\mathbb{R}^n\to\mathbb{R}$$

and a set

$$\mathbb{Y} = \{y_0, y_0 + d_1, ..., y_0 + d_n\}$$

poised for linear interpolation

The Simplex Gradient of f over  $\mathbb{Y}$ , denoted by  $\nabla_S f(\mathbb{Y})$ , is the gradient of the linear interpolation of f over  $\mathbb{Y}$ 

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## An equivalent definition

 $\begin{array}{l} \text{Suppose } \mathbb{Y} \text{ is poised} \\ \text{Then} \end{array}$ 

$$\nabla_{\mathcal{S}}f(\mathbb{Y}) = L^{-\top}\delta_{\mathcal{S}}^{f(\mathbb{Y})}$$

where

$$L = L(\mathbb{Y}) = [y_0 + d_1 - y_0 \cdots y_0 + d_n - y_0] = [d_1 \cdots d_n],$$

$$\delta_{S}^{f(\mathbb{Y})} = \begin{bmatrix} f(y_{0} + d_{1}) - f(y_{0}) \\ \vdots \\ f(y_{0} + d_{n}) - f(y_{0}) \end{bmatrix}$$

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## Centred Simplex Gradient, CSG

The reflection a poised set  $\mathbb{Y}^+ = \{y_0, y_0 + d_1, ..., y_0 + d_n\}$  through  $y_0$ 

• 
$$\mathbb{Y}^- = \{y_0, y_0 - d_1, ..., y_0 - d_n\}$$

•  $\mathbb{Y}^-$  is also poised

The Centred Simplex Gradient of f over  $\mathbb{Y} = \mathbb{Y}^+ \cup \mathbb{Y}^-$ , denoted by  $\nabla_{CS} f(\mathbb{Y})$ , is given by

$$abla_{CS}f(\mathbb{Y}) = rac{1}{2}\left(
abla_{S}f(\mathbb{Y}^{+}) + 
abla_{S}f(\mathbb{Y}^{-})
ight)$$

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$$abla_{CS}f(\mathbb{Y})=rac{1}{2}\left(
abla_{S}f(\mathbb{Y}^{+})+
abla_{S}f(\mathbb{Y}^{-})
ight)$$

Is equivalent to

$$abla_{\textit{CS}} f(\mathbb{Y}) = \left(L^+ - L^-\right)^{- op} \left(\delta_{\mathcal{S}}^{f(\mathbb{Y}^+)} - \delta_{\mathcal{S}}^{f(\mathbb{Y}^-)}
ight)$$

where  $L^+ = L(\mathbb{Y}^+), \quad L^- = L(\mathbb{Y}^-)$ 

## Approximation accuracy

Let 
$$\Delta = \overline{\operatorname{diam}}(\mathbb{Y}^+) \coloneqq \max_i \left\{ \|y_i - y_0\| 
ight\}$$
  
Then

• 
$$\|\nabla f(y_0) - \nabla_S f(y_0)\| = \mathcal{O}(\Delta)$$

• 
$$\|\nabla f(y_0) - \nabla_{CS} f(y_0)\| = \mathcal{O}(\Delta^2)$$

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## In this talk ...

CSG requires

- A point of interest  $y_0$
- A poised set  $\mathbb{Y}^+$
- An exact reflection set  $\mathbb{Y}^-$

What if the reflection set of  $\mathbb{Y}^+$  is not exact?

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## Misaligned reflection set

Suppose the reflection set of  $\ensuremath{\mathbb{Y}}^+$  is not exact

•  $\widetilde{\mathbb{Y}}$  is provided instead, with  $\widetilde{\mathbb{Y}}\approx\mathbb{Y}^-$ 

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## Misaligned reflection set

Suppose the reflection set of  $\ensuremath{\mathbb{Y}}^+$  is not exact

•  $\widetilde{\mathbb{Y}}$  is provided instead, with  $\widetilde{\mathbb{Y}}\approx\mathbb{Y}^-$ 

Centred Simplex Gradient:

$$\nabla_{CS} f(\mathbb{Y}) = \left(L^{+} - L^{-}\right)^{-\top} \left(\delta_{S}^{f(\mathbb{Y}^{+})} - \delta_{S}^{f(\mathbb{Y}^{-})}\right)$$

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## Misaligned reflection set

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•  $\widetilde{\mathbb{Y}}$  is provided instead, with  $\widetilde{\mathbb{Y}}\approx\mathbb{Y}^-$ 

Centred Simplex Gradient:

$$abla_{CS}f(\mathbb{Y}) = \left(L^+ - L^-
ight)^{- op} \left(\delta_S^{f(\mathbb{Y}^+)} - \delta_S^{f(\mathbb{Y}^-)}
ight)$$

An 'obvious' approximate gradient would be

$$\nabla f(y_0) \approx \left(L^+ - \widetilde{L}\right)^{-\top} \left(\delta_{\mathcal{S}}^{f(\mathbb{Y}^+)} - \delta_{\mathcal{S}}^{f(\widetilde{\mathbb{Y}})}\right)$$

However...

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## Approximation accuracy

Let 
$$\Delta = \overline{\operatorname{diam}}(\mathbb{Y}^+) \coloneqq \max_i \left\{ \|y_i - y_0\| 
ight\}$$
  
Then

• 
$$\|\nabla f(y_0) - \nabla_S f(y_0)\| = \mathcal{O}(\Delta)$$

• 
$$\|\nabla f(y_0) - \nabla_{CS} f(y_0)\| = \mathcal{O}(\Delta^2)$$

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## Approximation accuracy

Let 
$$\Delta = \overline{\operatorname{diam}}(\mathbb{Y}^+) \coloneqq \max_i \{ \|y_i - y_0\| \}$$
  
Then

• 
$$\|\nabla f(y_0) - \nabla_S f(y_0)\| = \mathcal{O}(\Delta)$$
  
•  $\|\nabla f(y_0) - \nabla_{CS} f(y_0)\| = \mathcal{O}(\Delta^2)$   
•  $\|\nabla f(y_0) - (L^+ - \widetilde{L})^{-\top} (\delta_S^{f(\mathbb{Y}^+)} - \delta_S^{f(\widetilde{\mathbb{Y}})})\| = \mathcal{O}(\Delta^2) ?$ 

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## A simple example

Example. Let  $f = x^2$ ,  $y_0 = 0$ ,  $\mathbb{Y}^+ = \{0, \Delta\}$ ,  $\widetilde{\mathbb{Y}} = \{0, -0.9\Delta\}$ Then

$$L^{+} = \Delta$$
$$\widetilde{L} = -0.9\Delta$$
$$\delta_{S}^{f(\mathbb{Y}^{+})} = f(\Delta) - f(0) = \Delta^{2}$$
$$\delta_{S}^{f(\widetilde{\mathbb{Y}})} = f(-0.9\Delta) - f(0) = 0.81\Delta^{2}$$

So

$$\left(L^{+} - \widetilde{L}\right)^{-\top} \left(\delta_{S}^{f(\mathbb{Y}^{+})} - \delta_{S}^{f(\widetilde{\mathbb{Y}})}\right) = 0.1\Delta$$
$$\left\|\nabla f(y_{0}) - \left(L^{+} - \widetilde{L}\right)^{-\top} \left(\delta_{S}^{f(\mathbb{Y}^{+})} - \delta_{S}^{f(\widetilde{\mathbb{Y}})}\right)\right\| = 0.1\Delta = \mathcal{O}(\Delta)$$

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## Outline





#### 2 Adapted Centred Simplex Gradient

#### Error analysis





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## Structure of $\widetilde{\mathbb{Y}}$ relative to $\mathbb{Y}^-$

Let 
$$\mathbb{Y}^+ = \{y_0, y_0 + d_1, ..., y_0 + d_n\}, \widetilde{\mathbb{Y}} = \{y_0, y_0 - \widetilde{d}_1, ..., y_0 - \widetilde{d}_n\}$$



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# Structure of $\widetilde{\mathbb{Y}}$ relative to $\mathbb{Y}^-$

For all  $i \in \{1, ..., n\}$ ,

• The Stretching Parameter k<sub>i</sub> is given by

$$k_i = \frac{\left\|\widetilde{d}_i\right\|}{\left\|d_i\right\|}$$

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For all  $i \in \{1, ..., n\}$ ,

• The Stretching Parameter k<sub>i</sub> is given by

$$k_i = \frac{\left\|\widetilde{d}_i\right\|}{\left\|d_i\right\|}$$

• The Rotation Angle  $\theta_i$  is the angle between  $d_i$  and  $\tilde{d}_i$ , given by

$$\theta_i = \cos^{-1}\left(\frac{d_i^{\top}\widetilde{d}_i}{\|d_i\| \|\widetilde{d}_i\|}\right) \in [0,\pi]$$

## Adapted Centred Simplex Gradient, ACSG

The Adapted Centered Simplex Gradient of f over  $\mathbb{Y} = \mathbb{Y}^+ \cup \widetilde{\mathbb{Y}}$ , denoted by  $\nabla_{ACS} f(\mathbb{Y})$ , is given by

$$\nabla_{ACS} f(\mathbb{Y}) = \left( L^+ D - \widetilde{L} \right)^{-\top} \left( D \delta_{S}^{f(\mathbb{Y}^+)} - \delta_{S}^{f(\widetilde{\mathbb{Y}})} \right)$$

where

$$D = \begin{bmatrix} k_1^2 & & \\ & \ddots & \\ & & k_n^2 \end{bmatrix}$$

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where

$$D = \begin{bmatrix} k_1^2 & & \\ & \ddots & \\ & & & k_n^2 \end{bmatrix}$$

Note:

• When all  $\theta_i = 0$  and  $k_i = 1$ ,  $\nabla_{ACS} f(\mathbb{Y}) = \nabla_{CS} f(\mathbb{Y})$ 

## Outline



2 Adapted Centred Simplex Gradient

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## Error bound

Theorem.  $f \in C^{2+}$  on  $B_{\overline{\Delta}}(y_0)$  with constant C,  $\overline{\operatorname{diam}}(\mathbb{Y}^+), \overline{\operatorname{diam}}(\widetilde{\mathbb{Y}}) \leq \overline{\Delta}$ Then

$$\begin{aligned} \|\nabla f(y_0) - \nabla_{ACS} f(\mathbb{Y})\| &\leq \frac{K}{2} \max\left\{k_i^2\right\} \sqrt{n} \left\| \left(\widehat{L}^+ D - \widehat{\widetilde{L}}\right)^{-1} \right\| \max\left\{\theta_i\right\} \Delta \\ &+ \frac{C}{6} \max\left\{k_i^2 \left(1 + k_i\right)\right\} \sqrt{n} \left\| \left(\widehat{L}^+ D - \widehat{\widetilde{L}}\right)^{-1} \right\| \Delta^2 \end{aligned}$$

where

$$\Delta = \overline{\operatorname{diam}}(\mathbb{Y}^+), \ \ \widehat{L}^+ = \frac{1}{\Delta}L^+, \ \ \widehat{\widetilde{L}} = \frac{1}{\Delta}\widetilde{L}$$

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$$egin{aligned} \|
abla f(y_0) - 
abla_{\mathcal{ACS}} f(\mathbb{Y})\| &\leq \kappa_ heta \max\left\{ heta_i
ight\} \Delta + \kappa_\Delta \Delta^2 \ &= \mathcal{O}(\Theta \Delta + \Delta^2) \end{aligned}$$

I.e., ACSG has  $\mathcal{O}(\Theta\Delta + \Delta^2)$  accuracy, where  $\Theta = \max\{\theta_i\}$ 

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#### Error analysis

## **Proof overview**

**Part 1:** Suppose all  $\theta_i = 0$ , by Taylor expansion

$$f(y_0 + d_i) = f(y_0) + \nabla f(y_0)^\top d_i + \frac{1}{2} d_i^\top \nabla^2 f(y_0) d_i + \mathcal{O}(\Delta^3)$$
(1)

$$f(y_0 - \widetilde{d}_i) = f(y_0) - k_i \nabla f(y_0)^\top d_i + \frac{1}{2} k_i^2 d_i^\top \nabla^2 f(y_0) d_i + \mathcal{O}(\Delta^3)$$
(2)

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#### Error analysis

## Proof overview

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(2)

Applying  $k_i^2(1)$ -(2), we have

$$k_{i}^{2} (f(y_{0} + d_{i}) - f(y_{0})) - (f(y_{0} - \widetilde{d}_{i}) - f(y_{0}))$$
  
=  $\nabla f(y_{0})^{\top} (k_{i}^{2} d_{i} + k_{i} d_{i}) + \mathcal{O}(\Delta^{3})$  (3)

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=  $\nabla f(y_{0})^{\top} (k_{i}^{2} d_{i} + k_{i} d_{i}) + \mathcal{O}(\Delta^{3})$  (3)

Using techniques similar to Simplex Gradient analysis, we obtain

$$\|
abla f(y_0) - 
abla_{ACS} f(\mathbb{Y})\| \leq \kappa_\Delta \Delta^2$$

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**Part 2:** Suppose all  $k_i = 1$ , by Taylor expansion

$$f(y_0 + d_i) = f(y_0) + \nabla f(y_0)^\top d_i + \frac{1}{2} d_i^\top \nabla^2 f(y_0) d_i + \mathcal{O}(\Delta^3)$$
(4)

$$f(y_0 - \widetilde{d}_i) = f(y_0) - \nabla f(y_0)^\top A_{\theta_i} d_i + \frac{1}{2} d_i^\top A_{\theta_i}^\top \nabla^2 f(y_0) A_{\theta_i} d_i + \mathcal{O}(\Delta^3)$$
(5)

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$$f(y_0 - \widetilde{d}_i) = f(y_0) - \nabla f(y_0)^\top A_{\theta_i} d_i + \frac{1}{2} d_i^\top A_{\theta_i}^\top \nabla^2 f(y_0) A_{\theta_i} d_i + \mathcal{O}(\Delta^3)$$
(5)

Applying (4)-(5), we have

$$f(y_0 + d_i) - f(y_0 - \widetilde{d}_i)$$
  
=  $\nabla f(y_0)^\top (d_i + A_{\theta_i} d_i) + \frac{1}{2} d_i^\top (\nabla^2 f(y_0) - A_{\theta_i}^\top \nabla^2 f(y_0) A_{\theta_i}) d_i + \mathcal{O}(\Delta^3)$   
(6)

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Separate

$$abla^2 f(y_0) - A_{ heta_i}^\top 
abla^2 f(y_0) A_{ heta_i}$$

into two symmetric matrices  $S_1$  and  $S_2$ , so

$$\begin{split} \left| \frac{1}{2} d_i^\top \left( \nabla^2 f(y_0) - A_{\theta_i}^\top \nabla^2 f(y_0) A_{\theta_i} \right) d_i \right| &\leq \left| \frac{1}{2} d_i^\top S_1 d_i \right| + \left| \frac{1}{2} d_i^\top S_2 d_i \right| \\ &\leq \frac{1}{2} \left( \max\left\{ |\lambda_{S_1}| \right\} + \max\left\{ |\lambda_{S_2}| \right\} \right) \|d_i\|^2 \\ &\leq \kappa \max\left\{ \theta_i \right\} \Delta^2 \end{split}$$

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Using techniques similar to Simplex Gradient analysis, we obtain

$$\|
abla f(y_0) - 
abla_{ACS} f(\mathbb{Y})\| \le \kappa_{ heta} \max\left\{ heta_i
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$$\|
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Part 3: Combine Part 1 and Part 2

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## Comparison to the direct generalization

Two formulae:

• 
$$\nabla f(y_0) \approx \left(L^+ - \widetilde{L}\right)^{-\top} \left(\delta_S^{f(\mathbb{Y}^+)} - \delta_S^{f(\widetilde{\mathbb{Y}})}\right)$$
 (Direct Generalization)  
•  $\nabla f(y_0) \approx \left(L^+ D - \widetilde{L}\right)^{-\top} \left(D\delta_S^{f(\mathbb{Y}^+)} - \delta_S^{f(\widetilde{\mathbb{Y}})}\right)$  (ACSG)

Test problems:

• 
$$f(x) = \sum_{i=1}^{n} [\sin(ix_i) + \cos(ix_i)]$$
 at  $y_0 = e_1$   
•  $f(x) = e^{-\|x\|^2}$  at  $y_0 = e_1$ 

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## $\theta = 0, k = 0.75$



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### $\theta = 0, k = 1$



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## $\theta = 0, k = 1.25$



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## Other experiments

Comparison to the direct generalization:

- Fix  $\theta = 0.1$ , repeat previous experiments
- Result: Similar pattern as  $\theta = 0$

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## Other experiments

Comparison to the direct generalization:

- Fix  $\theta = 0.1$ , repeat previous experiments
- Result: Similar pattern as  $\theta = 0$

Relation of error to  $\theta$ :

- Fix  $k \approx 1$ , consider  $\theta \in \{1, 10^{-1}, 10^{-2}, 10^{-3}, 10^{-10}\}$ , shrink  $\Delta$
- Result: As  $\theta \to 0$ , error goes from  $\mathcal{O}(\Delta)$  to  $\mathcal{O}(\Delta^2)$

**Recall**: ACSG has  $\mathcal{O}(\Theta \Delta + \Delta^2)$  accuracy, where  $\Theta = \max\{\theta_i\}$ 

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## Other experiments

Relation of error to k:

- Fix  $\theta = 0$ , consider  $k \in \{1, 10^1, 10^2, 10^4, 10^{16}, 10^{64}, 10^{128}\}$ , shrink  $\Delta$
- Result: As  $k \to \infty$ , ACSG goes from CSG to SG

Proof:

$$\begin{split} &\lim_{k \to \infty} \left( L^+ D - \widetilde{L} \right)^{-\top} \left( D \delta_{\mathcal{S}}^{f(\mathbb{Y}^+)} - \delta_{\mathcal{S}}^{f(\widetilde{\mathbb{Y}})} \right) \\ &= \lim_{k \to \infty} \left( L^+ \right)^{-\top} D^{-\top} D \delta_{\mathcal{S}}^{f(\mathbb{Y}^+)} \\ &= \left( L^+ \right)^{-\top} \delta_{\mathcal{S}}^{f(\mathbb{Y}^+)} \\ &= \nabla_{\mathcal{S}} f(\mathbb{Y}^+) \end{split}$$

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## Conclusions

#### Summary

- We generalized CSG and developed ACSG
- ACSG has  $\mathcal{O}(\Theta\Delta + \Delta^2)$  accuracy, where  $\Theta = \max\{\theta_i\}$
- $\bullet$  When  $\mathbb {Y}$  is not perfectly symmetric, ACSG outperforms CSG
- ACSG could be used to reduce functions calls in DFO algorithms

Next steps

- $\bullet$  Develop algorithms to find the best pair of  $\mathbb{Y}^+$  and  $\widetilde{\mathbb{Y}}$  efficiently
- Explore properties of underdetermined and overdetermined ACSG

# Thank you

• Chen, Hare. Adapting the Centred Simplex Gradient to Compensate for Misaligned Sample Points. Preprint available by emailing yiwchen@student.ubc.ca or warren.hare@ubc.ca

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